Introduction to Distributed-Memory Computing

ICS432 Concurrent and High-Performance Programming

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More Concurrency

- So far we have talked about concurrency "within a box"
 - □ Within a processor
 - Pipelining
 - Multiple functional units
 - Instruction Level Parallelism
 - Hyper-Threading
 - Across processors
 - Multi-proc systems
 - Multi-core systems
 - Multi-proc/core systems

But this can only get us so far for many applications...

Toward Distributed Memory

- We saw that we go to concurrency for need of more CPU cycles (i.e., we want to use all cores)
- But that's often not enough and we can't use a single system anymore
- Reason #1: We need way more cycles than that in a single machine
- Reason #2: We need way more RAM than that in a single machine
- Solution: Use more than one machine

Example: Image Processing Filter

Say you want to apply a simple filter to a domain (image, computational fluid dynamics, etc.)





Sample Stencil App Code

Too Large?

- This is all well and good, but what if my array requires 8GB of memory and I only have 1GB of RAM?
- I could think of just relying on virtual memory
 This is bound to be very slow
- I could manage the reads and writes to disk myself
 - Could be a bit faster than virtual memory if I am really clever, but would be complicated and still slow
 - Called an "out of core" implementation
- Or, I could use 8 different machines with 1GB RAMs and run fast without really ever swapping between the memory and the disk!

Distributed Memory Programming

- So, I give you a bunch of individual hosts, all connected via a network
- The big question is: How do we write code for something like this?
- The application now consists of multiple processes running on different machines
 Each process can consist of multiple threads!
 Let's look at this on a picture

Distributed Memory Platform

hyper-threaded processor core

dual-core chip



dual-core system



Distributed Memory Platform

hyper-threaded processor core

dual-core chip

dual-core system





Cluster of dual-core systems

Distributed Memory Program



8 processes

Each process contains, for example, 4 threads
 2 threads are running on each core using hyper threading

Distributed Memory Program



Each process stores some data in the memory of its box

How do we even declare arrays?

- We cannot have a declaration of an NxN array any more, because that would not fit in memory
- Each process (running on a different system) must handle an array of size N x N/8
 - Each process allocates memory for 1/8 of the overall array
- This is the same kind of "cutting the image into slabs" approach as we would used for a shared-memory implementation...

Data Distribution



Data Distribution



Data Distribution



- Each piece of the image is stored in the memory of a different system
- A process running on one system can only "see" (i.e., address) the local image piece, and has no way to address other pieces: NO SHARED MEMORY
- This is what makes distributed memory programming MUCH harder than shared-memory programming

Boundaries!

One of the problems now is: what happens at the boundaries/edges of the image tiles?



process #1



- Process #1 needs pixels from process #2
- Process #2 needs pixels from process #1
- But processes cannot share memory because they're on different systems:
 - With multiple threads all on the same system, there is no notion that a thread can't see some data!
 - In fact, we use threads because we want them to see the data
 - But now we're forced to use processes, and on different machines to boot

Message-Passing

- Since processes cannot share memory, they have to exchange messages
 - "here are the pixels you need from me, give me the ones I need from you"
- This type of programming is called "messagepassing"
- Uses network communication

e.g., socket and TCP

- So your code will have special function calls:
 - □ Send(...)
 - □ Receive(...)
- We're getting further away from "simple" sharedmemory programming

SPMD Program

- So at this point, we could
 - implement 8 different programs
 - start them up somehow on different nodes of our cluster (for instance)
 - have them all somehow identify their left and right neighbors, if any
- Turns out that this is really cumbersome
 - And if I want to use 1000 processes, I have to write 1000 programs?
- Typically one uses/implements the notion of a process' rank

Process Ranks

- To identify the processes participating in the computation, each process is assigned an index from 0 to N-1
- Each process can find out what its rank is and how many processes there are in total



Communication Patterns



- Process 0 will send to 1 and receive from 1
- Process 1 will send to 0, receive from 0, send to 2, and receive from 2
- Process 7 will receive from 6 and send to 6

SPMD Programming

If every process can find out its rank and the total number of processes, then one can write a Single Program to operate on Multiple pieces of Data simultaneously (SPMD):

```
int main() {
    if (my_rank() == 0) {
        // talk to my below neighbor
    } else if (my_rank() == num_processes() -1) {
        // talk to my above neighbor
    } else {
        // talk to my above and below neighbors
    }
}
```

Ranks and Number of Processes

- For now we're going to assume we have the my_rank() and the num_processes() functions, and the all the logistics of starting up the processes is taken care of
 - The same assumption that we can make with OpenMP within a single machine
- But this can also be implemented by hand if necessary
- The way to write distributed memory programs is to rely on process ranks

Writing the SPMD Program

The pseudo-code of the SPMD program could then look like

int main() {
 int M = N/num_processes(); // assumed to be integer!
 int original_image[M][N];
 int new_image[M][N];

// load my part of the image from disk
// compute all the pixels that do not require communication
// send border pixels to my neighbor(s)
// receive border pixels from my neighbors()
// compute the remaining pixels
// save the new image to file in orderly fashion

Writing the SPMD Program

- For now, let's ignore the issue of loading/ writing files to disk
 - There are a lot of options here, simple/slow ones, and complex/fast ones
- Let's focus on computation and communication

Computing the "easy" pixels



Can be computed without communication

Requires pixels from neighbors

(note that process 0 and process N-1 can compute one more row than the others without any communication

Computing the "easy" pixels

```
for (j=0; j<N; j++) {
  if (my_rank() == 0) { // top process can compute an extra row
   new_image[0][j] = f ( original_image[0][j],
                         original_image[0][j-1], original_image[0][j+1],
                         original image[1][j]);
  }
 if (my_rank() == num_processes()-1) { // bottom process can compute
                                          // an extra row
   new_image[M-1][j] = f ( original_image[M-1][j],
                            original_image[M-1][j-1], original_image[M-1][j+1],
                            original image[M-2][j]);
 for (i=1; i<M-1; i++) // Everybody computes the "middle" M-2 rows
    new_image[i][j] = f ( original_image[i][j],
                         original_image[i+1][j], original_image[i-1][j],
                         original_image[i][j-1], original_image[i][j+1] );
```

Global/Local Index

- One of the reason why distributed memory programming is difficult is because of the discrepancy between "global" and "local" indices
- When I think "globally" of the whole image, I know where pixel at coordinates (100,100) is
- But when I write the code, I will not reference the pixel as image[100][100]!
- Let's look at this on an example

Global/Local Index



- The red pixel's global coordinates are (5,1)
 - The pixel on the 6th row and the 2nd column of the big array
- But when Process #1 references it, it must use coordinates (1,1)
 - The pixel on the 2nd row and the 2nd column of the tile that's stored in Process #1

Global/Local Index



// Shared-Memory
double array[8][8];
array[5][1] = 12;

// Distributed-Memory
double array[4][8];
array[1][1] = 12;

Message Passing

- Let's assume that we have a send() function that takes as argument
 - The rank of the destination process
 - An address in local memory
 - □ A size (in bytes)
- Let's assume that we have a recv() function that takes as argument
 - An address in local memory
 - □ A size (in bytes)

A Process' Memory

original image: MxN



Sending/Receiving Pixels

double buffer_top[N], buffer_bottom[N];

```
if (my_rank() != 0) { // receive from above neighbor
    send(my_rank()-1,&(original_image[0][0]),sizeof(double)*N);
    recv(buffer_top, sizeof(double)*N);
```

if (my_rank() != num_processes()-1) { // receive from below neighbor send(my_rank()+1, &(original_image[M-1][0]), sizeof(double)*N); recv(buffer_bottom, sizeof(double)*N); }

// assumes "non-blocking" sending

}

Computing Remaining Pixels

```
if (my_rank() != 0) { // update top pixels
   for (j=0; j<N; j++) {
      new_image[i][j] = f ( original_image[i][j],
                             original_image[i+1][j], buffer_top[0][j],
                             original_image[i][j-1], original_image[i][j+1]);
if (my rank() != N-1) { // update bottom pixels
   for (j=0; j<N; j++) {
      new_image[i][j] = f ( original_image[i][j],
                             buffer_bottom[0][j], original_image[i+1][j],
                             original_image[i][j-1], original_image[i][j+1]);
```

We're done!

- At this point, we have written the whole code
- What's missing is I/O:
 - Read the image in
 - Write the image out
- Dealing with I/O (efficiently) is a difficult problem, and we won't really talk about it in depth
- And of course we need to use a tool that provides the my_rank(), the num_processors(), the send() and the recv() functions
- Each process allocates 1xN + 1xN + 2(M/P)xN = (2M/ P+2)N pixels, where P is the number of processors
- Therefore, the total number of pixels allocated is: 2MN + 2NP
 - 2NP extra pixels allocated than in the sequential version
 - But it's insignificant when spread across multiple systems





Too hard?

- Clearly the previous example is a bit scary
- Many researchers in academia and industry are trying to make this better
 - Tons of libraries written by smart people so that you don't have to be
 - New languages / compilers
 - New programming models
 - Map-Reduce anyone?
 - New ways to think of applications

Distributed-Memory Computing

- Bottom-line: Distributed-Memory computing is not easy, but it's the only way to scale many applications
- As a result"parallel computing platforms" have been built for many decades
 - So-called "supercomputers"
- The main idea:
 - Get a bunch of individual systems (commodity computers, or cool custom computers)
 - Get a network (commodity switches, cool custom interconnects)
 - Install software to make it possible to write/run program
 - □ and off we go....

A host of parallel machines

- There are (have been) many kinds of parallel machines
- For the last 12 years their performance has been measured and recorded with the LINPACK benchmark, as part of Top500
- It is a good source of information about what machines are and how they have evolved
- Note that it's really about "supercomputers"

http://www.top500.org



What is **Beowulf**?

- An experiment in parallel computing systems
- Established <u>vision</u> of low cost, high end computing, with public domain software (and led to software development)
- Tutorials and book for best practice on how to build such platforms
- Today by Beowulf cluster one means a commodity cluster that runs Linux and GNU-type software
- Project initiated by T. Sterling and D. Becker at NASA in 1994



The Prettiest Supercomputer?

http://degiorgi.math.hr/~vsego/phun/ beautiful_supercomputer/



River-Water Cooled Supercomputer

<u>http://www.research.ibm.com/articles/</u> <u>superMUC.shtml</u>



Conclusion

Writing distributed memory code is much more complex than shared memory code

One must identify what must be communicated

- One must keep a mental picture of the memory across systems
- In addition to all the concerns we have mentioned in class
 - e.g., cache reuse, synchronization among threads
- □ And the typical problems of shared memory are still there
 - There can be "communication" deadlocks, race conditions, etc.
- Big "supercomputers" are amazing and expensive machines with a long and politically/economically-charged history
- Almost all of you will write some type of distributedmemory application (not necessarily High-Performance Computing, but using the same concepts)
- If you're into all this, take ICS632